

1. (a) First note that:

$$\langle \mathbf{x}, \mathbf{1} \rangle = \sum_{i=1}^n x_i$$

and

$$\|\mathbf{1}\|^2 = \langle \mathbf{1}, \mathbf{1} \rangle = \sum_{i=1}^n 1 = n.$$

We can compute the projection of  $\mathbf{x}$  onto  $\mathcal{M}$  using the general formula.

$$\begin{aligned} P_{\mathcal{V}}\mathbf{x} &= \frac{\langle \mathbf{x}, \mathbf{1} \rangle}{\|\mathbf{1}\|^2} \mathbf{1} \\ &= \left( \frac{1}{n} \sum_{i=1}^n x_i \right) \mathbf{1} \\ &= \bar{x} \mathbf{1} \\ &= (\bar{x}, \dots, \bar{x}) \end{aligned}$$

Since  $\mathbf{x} = P_{\mathcal{M}}\mathbf{x} + P_{\mathcal{V}}\mathbf{x}$ ,

$$\begin{aligned} P_{\mathcal{V}}\mathbf{x} &= \mathbf{x} - P_{\mathcal{M}}\mathbf{x} \\ &= (x_1, \dots, x_n) - (\bar{x}, \dots, \bar{x}) \\ &= (x_1 - \bar{x}, \dots, x_n - \bar{x}) \end{aligned}$$

In words,  $P_{\mathcal{V}}\mathbf{x}$  is the vector of deviations from the mean.

(b) Using the results above

$$\|P_{\mathcal{V}}\mathbf{x}\|^2 / \|\mathbf{1}\|^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$$

Which is (very close to) the sample variance.

(c) The angle is defined by

$$\begin{aligned} \cos \theta &= \frac{\langle P_{\mathcal{V}}\mathbf{x}, P_{\mathcal{V}}\mathbf{y} \rangle}{\sqrt{\|P_{\mathcal{V}}\mathbf{x}\|^2 \|P_{\mathcal{V}}\mathbf{y}\|^2}} \\ &= \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \sum_{i=1}^n (y_i - \bar{y})^2}} \end{aligned}$$

which is the correlation between  $\mathbf{x}$  and  $\mathbf{y}$ .

2. The following R commands will generate the plots.

- (a) `plot(ARMAacf(ar=c(1.2,-0.7),lag=15),type="h").`
- (b) `plot(ARMAacf(ar=c(-1,-0.6),lag=15),type="h").`
- (c) `plot(ARMAacf(ma=c(1.2,-0.7),lag=15),type="h").`
- (d) `plot(ARMAacf(ma=c(-1,-0.6),lag=15),type="h").`
- (e) `plot(ARMAacf(ar=0.7,ma=0.4,lag=15),type="h").`
- (f) `plot(ARMAacf(ar=0.7,ma=-0.4,lag=15),type="h").`

3. The important trigonometric formula here is

$$\cos \alpha \cos \beta = \frac{1}{2} [\cos(\alpha + \beta) + \cos(\alpha - \beta)].$$

To show weak stationarity we need to show that  $EY_t$  is constant and that  $\text{cov}(Y_{t+u}, Y_t)$  depends only on  $u$ . Now

$$E(Y_t) = \frac{1}{2\pi} \int_0^{2\pi} a \cos(\lambda t + \theta) d\theta = 0$$

and

$$\begin{aligned} \text{cov}(Y_{t+u}, Y_t) &= \frac{1}{2\pi} \int_0^{2\pi} a^2 \cos(\lambda(t+u) + \theta) \cos(\lambda t + \theta) d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} \frac{a^2}{2} [\cos(\lambda(2t+u) + 2\theta) + \cos(\lambda u)] d\theta \\ &= \frac{a^2 \cos \lambda u}{2}, \end{aligned}$$

which depends only on  $u$  and not  $t$ .

Showing strict stationarity is much harder. Let's just show that the distribution of  $Y_{t+u}$  does not depend on  $u$ . This means showing that

$$P[\cos(\lambda t + \theta) < y] = P[\cos(\lambda(t+u) + \theta) < y]$$

for any value of  $y$ . This in turn will follow if we can show

$$P[\cos(\theta) < y] = P[\cos(\theta + c) < y]$$

for every  $c$ , because both the probabilities above must be equal to  $P[\cos(\theta) < y]$ .